

STUDY OF ELECTROMAGNETIC PHENOMENA AND ITS MAIN PARAMETERS IN THE CRUCIBLE OF INDUCTION FURNACES DURING SMELTING STEEL 20GL

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Abstract

This article is devoted to the study of electromagnetic phenomena in induction furnaces for smelting steel. The main objectives of this article are to study electromagnetic phenomena in liquid metal in a crucible to estimate electrical losses in an inductor, as well as to obtain calculation formulas for active power P_M released in liquid steel, and reactive power Q_M arising in liquid steel.



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The listed parameters are necessary to calculate the optimal thickness of the lining of induction furnaces in order to increase the service life of the lining and increase the number of heats.

In the article were used: the mathematical expression of the solution of the equation through the complex functions $J_{\vartheta}(x)$ is represented by a graphical interpretation (obtained on the basis of a calculation using the IN program); Euler - Bessel equation; complex form of the Poynting vector S_R ; incidence of a cylindrical electromagnetic wave on a solid metal cylinder with a diameter of D_M for crucible of induction furnaces (ICF-6).

Keywords: electromagnetic wave, magnetic field strength, electric field strength, cylindrical wave, Poynting vector, active power, reactive power, coefficients

1. Introduction

This article is devoted to the study of electromagnetic phenomena in 6 ton induction furnaces when smelting steel grade 20GL (analogue for EU=G21Mn5 and USA = A352GrLCC) in the Subsidiary Foundry Mechanical Plant (FMP) in Tashkent. To study electromagnetic phenomena in a liquid metal in a crucible to estimate electrical losses in an inductor, it is necessary to use the rotor of the magnetic (1) and electric (2) field strengths in cylindrical coordinates. [4,2]

During most of the melting process, exactly from the moment when a part of the steel charge is melted, in which the still unmelted pieces can be accommodated, the steel charge is represented as a solid cylindrical block with $\mu_r = 1$. Steel satisfies this condition at temperatures above the Curie point. Therefore, the induction crucible furnace (ICF) is a cylindrical system "inductor - metal" (Fig. 1): the vector of the magnetic field strength is directed parallel to the axis of the cylindrical wave (H = H_z ; $H_{\psi} = 0$; $H_R = 0$); the vector of the electric field strength is directed tangentially to the circles, the centers of which lie on the axis of the cylindrical inductor (E = E_{ψ} ; $E_z = 0$; $E_R = 0$) [2,4].





Figure 1 – The incidence of a cylindrical electromagnetic wave on a solid metal

cylinder with a diameter D_{M} (for ICF -6 in FMP $D_{M} = 1050$ mm):

I - current in the inductor; H_3 , $H_π$, H_R μ $H_μ$ - magnetic field strength in the gap, on the surface, at a point with radius R and on the axis of the metal cylinder, respectively; $E_π$ μ E_R – the electric field strength on the surface and at a point with a radius R; ψ - meridian angle (longitude); the O-O axis shows the diagram of the instantaneous values of the magnetic field strength; arrows indicate the direction of the corresponding electric lines of force (line of conduction currents J) along the cross-section of the cylinder [2]

2. Methods

In cylindrical coordinates, the rotor of the magnetic (1) and electric (2) field strengths can be solved, respectively, through the determinant

 $\begin{bmatrix} 1_{\rm R} & 1_{\psi} & 1_{\rm z} \\ \partial & \partial & \partial \end{bmatrix} = \frac{1_{\rm R}}{2} =$

$$[\nabla H] = \begin{vmatrix} \partial & & + & + & - \\ \partial \partial R & \partial & & + & + \\ H_R & H_{\psi} & H_z \end{vmatrix} = \mathbf{1}_R \frac{\partial}{\partial \psi} H_z + \mathbf{1}_{\psi} \frac{\partial}{\partial z} H_R + \mathbf{1}_z \frac{\partial}{\partial R} H_{\psi} - \mathbf{1}_R \frac{\partial}{\partial z} H_{\psi} - \\ \mathbf{1}_{\psi} \frac{\partial}{\partial R} H_z - \mathbf{1}_z \frac{\partial}{\partial \psi} H_R.$$
(1)



$$[\nabla E] = \begin{vmatrix} W EB OF SCIENTIST: INTERNATIONAL \\ SCIENTIFIC RESEARCH JOURNAL \\ ISSN: 2776-0979, Volume 3, Issue 6, June, 2022 \end{vmatrix}$$
$$[\nabla E] = \begin{vmatrix} 1_{R} & 1_{\psi} & 1_{z} \\ \frac{\partial}{\partial R} & \frac{\partial}{\partial \psi} & \frac{\partial}{\partial z} \\ E_{R} & E_{\psi} & E_{z} \end{vmatrix}$$
$$= 1_{R} \frac{\partial}{\partial \psi} E_{z} + 1_{\psi} \frac{\partial}{\partial z} E_{R} + 1_{z} \frac{\partial}{\partial R} E_{\psi} - 1_{R} \frac{\partial}{\partial z} E_{\psi} - 1_{\psi} \frac{\partial}{\partial R} E_{z}$$
$$- 1_{z} \frac{\partial}{\partial \psi} E_{R}.$$
(2)

After transformations received:

$$\begin{split} \nabla^2 H_z &= \frac{\partial^2 H_z}{\partial R^2} + \frac{1}{R} \frac{\partial H_z}{\partial R};\\ \nabla^2 E_\psi &= \nabla^2 E_\psi - \frac{1}{R^2} E_\psi = \frac{\partial^2 E_\psi}{\partial R^2} + \frac{1}{R} \frac{\partial E_\psi}{\partial R} - \frac{1}{R^2} E_\psi. \end{split}$$

Vector Laplacians for the magnetic intensity vector H_z field and vector of electric field strength E_{ψ} at a distance R for a conductive medium:

$$\frac{\partial^2 H_z}{\partial R^2} + \frac{1}{R} \cdot \frac{\partial H_z}{\partial R} = \frac{j \omega \mu_{a \delta c} H_z}{\rho_M};$$
(3)

$$\frac{\partial^{2} E_{\psi}}{\partial R^{2}} + \frac{1}{R} \cdot \frac{\partial E_{\psi}}{\partial R} - \frac{1}{R^{2}} \cdot E_{\psi} = \frac{j \omega \mu_{abc} E_{\psi}}{\rho_{M}}.$$
 (4)

Considering that

$$-\frac{j\omega\mu_{abc}}{\rho_{M}} = (j^{\frac{3}{2}} \cdot \frac{\sqrt{2}}{\delta_{eqv}})^{2}, \qquad (5)$$

Eqs. (3) and (4) can be given a simpler form by substituting the complex variable instead of the only independent variable R $\xi = \left(j^{\frac{3}{2}} \cdot \frac{\sqrt{2}R}{\delta_{eqv}}\right)^2$ and replace partial derivatives with ordinary ones (since H_z and E_{\u03c0} are functions of the only variable):

$$\frac{\partial^{2} H_{z}}{\partial \xi^{2}} + \frac{1}{\xi} \cdot \frac{\partial H_{z}}{\partial \xi} + H_{z} = 0;$$
 (6a)

$$\frac{\partial^2 E_{\psi}}{\partial \xi^2} + \frac{1}{\xi} \cdot \frac{\partial E_{\psi}}{\partial \xi} + \left(1 - \frac{1}{\xi^2}\right) \cdot E_{\psi} = 0.$$
 (6b)





Equations (6a) and (6b) represent special cases of a homogeneous linear differential equation of the second order with the index ϑ (the so-called Euler - Bessel equation):

$$\frac{\partial^2 y}{\partial x^2} + \frac{1}{x} \cdot \frac{\partial y}{\partial x} + (1 - \frac{\theta^2}{x^2}) \cdot y = 0.$$
(7)

i.e., equation (6a) is an equation with the index $\vartheta = 0$, equation (6b) - with the index $\vartheta = 1$. Their solutions are represented as a linear combination of a cylindrical function of the first kind $J_{\vartheta}(x)$ and a cylindrical function of the third kind of the second kind $H_{\vartheta}^{(2)}(x)$:

$$y = A_{\vartheta} J_{\vartheta}(x) + C_{\vartheta} H_{\vartheta}^{(2)}(x).$$
(8)

Given the nature of the change in function J_{ϑ} and $H_{\vartheta}^{(2)}$ on the complex variable ξ , we can say that the first term in expression (8) describes the incident wave propagating from the cylinder surface to its axis, and the second term describes the reflected wave propagating from the cylinder axis to the surface. A solid cylinder has no reflective surfaces, so there will be no reflected wave, i.e. the constant of integration C_{ϑ} is equal to zero.

3. Results and Discussion

The mathematical expression of the solution to equation (8) in terms of complex functions $J_{\vartheta}(x)$ is represented by a graphical interpretation equations of magnetic and electric fields in a liquid metal in the form of the dependence of the relative modulus of complex vectors of intensity:

magnetic field

$$|\mathbf{H}|_{*} = \frac{|\mathbf{H}_{\mathbf{Z}}|}{|\mathbf{H}_{\Pi}|} = \varphi'\left(\frac{\mathbf{R}}{\mathbf{R}_{\Pi}}\right). \tag{9}$$

and electric field strength

$$|\mathbf{E}|_* = \frac{|\mathbf{E}_{\psi}|}{|\mathbf{E}_{\Pi}|} = \varphi^{\prime\prime} \left(\frac{\mathbf{R}}{\mathbf{R}_{\Pi}}\right). \tag{10}$$

and, which is the same, the complex vector of the conduction current density

$$|\mathbf{J}|_* = \frac{|\mathbf{J}_{\Psi}|}{|\mathbf{J}_{\Pi}|} = \phi^{\prime\prime}\left(\frac{\mathbf{R}}{\mathbf{R}_{\Pi}}\right).$$
(11)



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on the relative volume radius of $20\Gamma \Lambda$ (analogue for EU=G21Mn5 and USA = A352GrLCC) liquid steel in the ICF-6 crucible $R_* = R/R_{\pi}$. It should be borne in mind that the value $R_* = 0$ corresponds to the crucible axis, a $R_* = 1$ - inner surface of the crucible.



Figure 2 – Distribution of the relative modulus of the complex vectors of the magnetic field strength $|H|_{*}$ (a), electric field strength $|E|_{*}$ and conduction current density $|J|_{*}$ (6) in liquid metal ICF-6 ($D_{M} = 1050 \text{ mm}$) (numbers near curves – values D_{M}/δ_{eqv} ; - exponent built for $D_{M}/\delta_{eqv} = 15$)

Argument values D_M/δ_{eqv} (see Fig. 1) for each curve correspond to the frequency (table N^o 1) according to the formula

$$f=\frac{500^2\rho_{\scriptscriptstyle M}}{\mu_r\delta_{eqv}^2}=\frac{0.35}{\delta_{eqv}^2}\,,$$

where $\rho_{M} = 140 \cdot 10^{-8} \text{ Om} \cdot \text{m} - \text{for liquid steel brands 20} \Gamma \Pi (\mu_{r} = 1);$ $D_{M} = 1050 \text{ mm} = 1.05 \text{ m}.$

Based on the results of numeric values D_M/δ_{eqv} the curves (see Fig. 2) correspond to the values of the current frequency f (table N^o 1).

D_{M}/δ_{eqv}	3	6	9	12	15
f, Hz	2.9	11.4	25.7	45.7	71.4

Table 1-Results of calculating compliance





Based on the results of numeric values $\frac{D_M}{\delta_{eqv}}$ the curves (Fig. 2) correspond to the values of the metal diameter in the crucible D_M (table N^o 2).

Table 2- Results of calculating compliance

D_{M}/δ_{eqv}	3	6	9	12	15
D _м , мм	114	227	340	453	567

A cylindrical wave carries electromagnetic energy determined by the vector of energy flux density per unit time S_R . In complex form, the Poynting vector S_R is the vector product of the complex of the electric field strength E_{ψ} by the conjugate complex of the magnetic field strength H_z

$$S_{\rm R} = 0.5 [E_{\rm \psi} H_{\rm z}^*].$$
 (12)

The scalar expression for the complex value of the power flux through the side surface of a metal cylinder with a diameter D_M , which is numerically equal to the lateral surface area S_{act} , allows one to obtain calculation formulas for the active power P_M (15) according to (13), released in liquid steel, and the reactive power Q_M (16), according to (14) arising in liquid steel [4]:

a) active power flux density, characterizing the rate of conversion of electromagnetic field energy into heat, kW/m²:

where

$$ReS = q_{act} \approx 2 \cdot 10^{-6} (IN_1)^2 \sqrt{\rho_m \cdot \mu_r \cdot f},$$

$$0^{-6} \approx \frac{2\pi \cdot 10^{-6}}{\sqrt{10}};$$
(13)

 $(IN_1) = \frac{IN}{h_{\mu}}$ - flooring of the inductor current, which determines the magnitude of the magnetic field strength on the inner surface and in the cavity of the inductor, $\frac{A}{m}$. b) the reactive power flux density, which characterizes the rate of conversion of the energy of the electromagnetic field from an electric form to a magnetic form and vice

versa, kW/m²:

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 $2 \cdot 1$

ImS =
$$q_{\text{reactive}} \approx 2 \cdot 10^{-6} (IN_1)^2 \sqrt{\rho_M \cdot \mu_r \cdot f}$$
. (14)

$$P_{M} = \text{ReS} \cdot S_{act} k_{MP} \approx 2 \cdot 10^{-6} (\text{IN}_{1})^{2} \pi D_{M} h_{M} \sqrt{\rho_{M} \mu_{rM}} f k_{MP} \approx$$

$$\approx 6.28 \cdot 10^{-6} (\text{IN}_{1})^{2} D_{M} h_{M} \sqrt{\rho_{M}} f k_{MP} = 2.4 \cdot 10^{-7} (\text{IN}_{1})^{2} k_{MP}, \text{ kW}; \qquad (15)$$

$$Q_{\rm M} = \operatorname{Im} S \cdot S_{\rm act} k_{\rm MQ} \approx 2 \cdot 10^{-6} (\mathrm{IN}_1)^2 \pi D_{\rm M} h_{\rm M} \sqrt{\rho_{\rm M} \mu_{\rm rM}} f k_{\rm MQ}$$
(16)



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$$Q_{\rm M} = 6.28 \cdot 10^{-6} (IN_1)^2 D_{\rm M} h_{\rm M} \sqrt{\rho_{\rm M}} f k_{\rm MQ} = 1.92 \cdot 10^{-7} (IN_1)^2 k_{\rm MQ}, kW.$$

where $\rho_{M} = 140 \cdot 10^{-8} \text{ Om} \cdot \text{m} - \text{for liquid steel brands 20} \Gamma \Pi (\mu_{r} = 1);$ $S_{act} = \pi D_{M} h_{M} \approx 4.53 \text{ m}^{2} - \text{the area of the side ("active") surface of the heated volume of liquid metal in the ICF crucible with a diameter <math>D_{M} = 1.05 \text{ m} \text{ m}$ height $h_{M} = 1.375 \text{ m};$ $2 \cdot 10^{-6} \approx \frac{2\pi \cdot 10^{-6}}{\sqrt{10}} - \text{coefficient};$

 $6.28 \cdot 10^{-6} \approx 2\pi \cdot 10^{-6}$ – coefficient;

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Figure 3 - Curves for determining the coefficients of active and reactive power

 $k_{\scriptscriptstyle MP},k_{\scriptscriptstyle MQ}$ - active and reactive power coefficients, respectively, taking into account the peculiarities of the physical processes of propagation and attenuation of cylindrical electromagnetic waves in the liquid metal ICF-6 and depending on the relative diameter of the cylinder $D_{\scriptscriptstyle M}/\delta_{eqv}$.

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